# **Domain theory and denotational semantics of functional programming**

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# What is denotational semantics?

Very abstract answer:

types are objects of a category,

programs are morphisms of this category.

Concrete examples:

- 1. category of sets (when it works).
- 2. categories of domains.
- 3. realizability toposes.
- 4. categories of games.

#### Why denotational semantics?

- 1. Mathematical models aid program verification.
- 2. They guide the construction of programming languages.
- Sometimes they allow one to discover new algorithms.
   Games. (Un)decidability of observational equivalence.
   Domains. (Un)decidability of function equality.
- 4. (Fill in your favourite answer here.)

# Why various kinds of denotational semantics?

Different mathematical aspects are addressed/emphasized: Domains. Finite approximation of infinite objects. Realizability. Constructive logic and computability. Games. Interaction, sequentiality.

## **Operational versus denotational semantics**

Operational semantics tells you how your programs are run. Denotational semantics tells you what your programs compute.

# **Operational versus denotational semantics**

Definition, to be made precise:

Adequacy. For observable types, the two agree. Full abstraction. Operational and semantic equivalence agree. Universality. All computable elements are programmable.

Universality  $\implies$  full abstraction  $\implies$  adequacy.

The converses fail.

## **One would like**

Types are sets.

Programs are functions.

Life would be much simpler if this were always possible (but perhaps less exciting).

(Synthetic domain theory rescues this wish.)

#### When do plain sets work?

E.g.

- 1. Gödel's system T: typed  $\lambda$ -calculus with primitive recursion.
- 2. Martin-Löf type theory.
- 3. Typed  $\lambda$ -calculus with (co)inductive types.

(But, for all I know, full abstraction for these may fail.)

# When plain sets don't work?

E.g.

- 1. Function recursion.
- 2. Type recursion, e.g.  $D \cong (D \to \text{Bool})$ .
- 3. Certain total functionals.
  - a. Fan functional.
  - b. Bar recursion.

Dana Scott (1969, 1972) proposed to use domains.

Ershov independently (motivation higher-type computability).

#### **Precursors of domain theory**

Kleene's recursion theorem.

Can find f such that f = F(f).

Myhill-Shepherdson theorem.

Computable functions  $(\mathbb{N} \to \mathbb{N}) \to (\mathbb{N} \to \mathbb{N})$  are continuous. Rice–Shapiro theorem.

Semidecidable subsets of  $\mathcal{P} \mathbb{N}$  are Scott open.

Platek's approach to Kleene-Kreisel higher-type computability.

E.g. which  $((\mathbb{N} \to \mathbb{N}) \to \mathbb{N}) \to \mathbb{N}$  are computable?

### What is a domain?

A set, with concrete, finite elements, together with ideal, infinite elements such that ideal elements are uniquely determined by their concrete approximations.

This can be made precise in a number of ways.

# Example

Consider programs (in any suitable language) that output bits either for ever, or else until they get stuck (in an infinite loop). E.g.

Domain-theoretic denotations:

(a)  $(01)^{\omega}$ , (b)  $\epsilon$ , (b) 01.

# **Example continued**

See whiteboard for a picture of the Cantor tree.

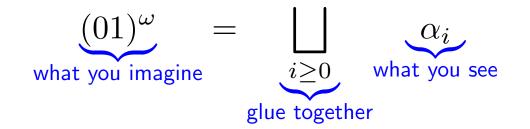
The runs of such programs correspond to paths in the Cantor tree.

E.g. (1) corresponds to the path



## **Concrete versus ideal**

Using notation to be made precise later:



Terminologies for this operation: join, supremum, least upper bound.

The set is 
$$D = \underbrace{\{0,1\}^*}_{\text{nodes of the tree}} \cup \underbrace{\{0,1\}^\omega}_{\text{infinite paths}}$$
.

For  $\alpha, \beta \in D$ , write  $\alpha \sqsubseteq \beta$ to mean that  $\alpha$  is a prefix of  $\beta$ .

This is a *partial order*:

Reflexivity.  $\alpha \sqsubseteq \alpha$ .

Transitivity.  $\alpha \sqsubseteq \beta \sqsubseteq \gamma \implies \alpha \sqsubseteq \gamma$ .

Anti-symmetry.  $\alpha \sqsubseteq \beta \& \beta \sqsubseteq \alpha \implies \alpha = \beta$ .

For any path  $\alpha_0 \sqsubseteq \alpha_1 \sqsubseteq \alpha_2 \sqsubseteq \cdots \sqsubseteq \alpha_i \sqsubseteq \cdots$ there is  $\beta \in D$  such that 1.  $\alpha_i \sqsubseteq \beta$  for all *i*. 2. If, for another  $\beta' \in D$ , 1'.  $\alpha_i \sqsubseteq \beta'$  for all *i*, then  $\beta \sqsubseteq \beta'$ .

For any path

 $\alpha_0 \sqsubseteq \alpha_1 \sqsubseteq \alpha_2 \sqsubseteq \cdots \sqsubseteq \alpha_i \sqsubseteq \cdots \sqsubseteq \beta \sqsubseteq \beta'$ 

there is  $\beta \in D$  such that

1.  $\alpha_i \sqsubseteq \beta$  for all *i*. ( $\beta$  is an upper bound of the sequence  $\alpha_i$ .)

2. If, for another  $\beta' \in D$ ,

1'.  $\alpha_i \sqsubseteq \beta'$  for all i, ( $\beta'$  is an other upper bound.) then  $\beta \sqsubseteq \beta'$ . (So  $\beta$  is the *least* upper bound.)

For any path  $\alpha_0 \sqsubset \alpha_1 \sqsubset \alpha_2 \sqsubset \cdots \sqsubset \alpha_i \sqsubseteq \cdots$ there is  $\beta \in D$  such that 1.  $\beta$  is an upper bound of the sequence  $\alpha_i$ . 2.  $\beta$  is below any other upper bound  $\beta'$ . This  $\beta$  is unique. Why? We write  $\beta = \bigsqcup_i \alpha_i$ .



D is an  $\omega$ -complete poset.

Sometimes domain is taken to mean  $\omega$ -complete poset with a least element  $\perp$ .

In this example,  $\perp$  is the empty sequence  $\epsilon$ .

# Another example: lazy lists in Haskell

For any type  $\sigma$ , there is a type  $[\sigma]$  of finite and infinite lists. It has the following elements:

1. The bottom sequence "[".

- 1'. More generally, " $[x_1, x_2, \ldots, x_n]$ " with  $x_i \in d$ .
- 2. Their terminated versions " $[x_1, x_2, \ldots, x_n]$ ".
- 3. Infinite sequences " $[x_1, x_2, \ldots, x_n, \ldots]$ "

and nothing else

**Order**: To be added. Board for the moment.

# **Simpler examples**

The type Bool in Haskell. Has three elements: True, False,  $\perp$ . Order: True and False are maximal,  $\perp$  is minimal. The type Integer in Haskell. Has all the integers plus  $\perp$ . Order: Integers are maximal,  $\perp$  is minimal.

All paths are trivial. The orders are  $\omega$ -complete.

# Semantics of programs and of function types

If two types  $\sigma$  and  $\tau$  are interpreted as domains D and E, then the function type  $(\sigma \to \tau)$  is interpreted as a domain  $(D \to E)$ .

Question. What  $(D \rightarrow E)$  should/can be?

1. All functions?

2. The computable functions?

Answer. Something in between.

3. The continuous functions.

Why? Answer postponed until we see some examples.

## **Continuity** — **computational motivation**

A function  $f: D \to E$  is continuous if finite parts of f(x) depend only on finite parts of x.

# **Continuity** — a special case first

Consider  $D = \{0, 1\}^* \cup \{0, 1\}^\omega$  ordered by prefix.

Definition.  $f: D \rightarrow D$  is monotone if

 $\alpha \sqsubseteq \beta \implies f(\alpha) \sqsubseteq f(\beta).$ 

If you supply more input, you get more output.

Definition. f is of finite character if

whenever  $\beta \sqsubseteq f(\alpha)$  for  $\beta$  finite,

there is  $\alpha' \sqsubseteq \alpha$  finite such that already  $\beta \sqsubseteq f(\alpha')$ .

## **Continuity** — a special case first

Theorem. For  $f: D \rightarrow D$  monotone, TFAE:

- 1. f is of finite character.
- 2. For every path

$$\alpha_0 \sqsubseteq \alpha_1 \sqsubseteq \alpha_2 \sqsubseteq \cdots \sqsubseteq \alpha_i \sqsubseteq \cdots$$

with

$$\alpha_{\infty} = \bigsqcup_{i} \alpha_{i}$$

one has

 $f(\alpha_{\infty}) = \bigsqcup_{i} f(\alpha_{i}).$ 

# **Continuity** — a special case first

Theorem. For  $f: D \rightarrow D$  monotone, TFAE:

- 1. f is of finite character.
- 2. For every path

$$\alpha_0 \sqsubseteq \alpha_1 \sqsubseteq \alpha_2 \sqsubseteq \cdots \sqsubseteq \alpha_i \sqsubseteq \cdots$$

one has

$$f(\bigsqcup_i \alpha_i) = \bigsqcup_i f(\alpha_i).$$

**Proof.** Exercise! Hint. First show that  $\alpha'$  is finite iff whenever  $\alpha' \sqsubseteq \bigsqcup_i \alpha_i$  for  $\alpha_i$  ascending, there is *i* such that already  $\alpha' \sqsubseteq \alpha_i$ .  $\Box$ 

# **Continuous function**

We make the previous theorem into a definition:

Definition. A function of domains is continuous iff

- 1. it is monotone, and
- 2. it preserves joins of ascending sequences.

#### **Interpretation of function types**

If two types  $\sigma$  and  $\tau$  are interpreted as domains D and E, then the function type  $(\sigma \rightarrow \tau)$  is interpreted as the domain  $(D \rightarrow E)$ .

Definition.  $(D \rightarrow E) = \text{set of continuous functions } D \rightarrow E$  ordered pointwise.

This means:  $f \sqsubseteq g$  iff  $f(x) \sqsubseteq g(x)$  for all  $x \in D$ .

**Theorem.** If D and E are domains, then so is  $(D \rightarrow E)$ .

# Some examples.

Use board.

#### **Products**

If two types  $\sigma$  and  $\tau$  are interpreted as domains D and E, then the product type  $(\sigma \times \tau)$  is interpreted as the domain  $(D \times E)$ .

**Definition.**  $(D \times E) = \text{cartesian product ordered coordinatewise.}$ 

This means:  $(x, y) \sqsubseteq (x', y')$  iff  $x \sqsubseteq x'$  and  $y \sqsubseteq y'$ .

Theorem. If D and E are domains, then so is  $(D \times E)$ .

#### Note on Haskell products and function types

Interpreted as  $(D \times E)_{\perp}$  and  $(D \to E)_{\perp}$ .

E.g. the following two functions are different (using seq): f,g :: a -> b f = f g x = g x Then seq f True diverges, but seq g True evaluates to True.

#### Note on Haskell products and function types

So,

1. Haskell products are not categorical, and

2. Haskell is not cartesian or monoidal closed.

In particular,  $\operatorname{curry}(\operatorname{uncurry}(f)) \neq f$  in general.

### Interaction between products and function spaces

Theorem. Continuous functions of domains form a cartesian closed category.

This amounts to:

 The evaluation function eval: (D → E) × D → E defined by eval(f, x) = f(x) is continuous.
 If f: C × D → E is continuous, then so is the function f̄: C → (D → E) defined by f̄(x) = λy.f(x, y).

# **Consequence of cartesian closedness**

Theorem. If a function is  $\lambda$ -defined from continuous functions, then it is itself continuous.

Application. Consider a functional programming language based on the simply typed  $\lambda$ -calculus, with some primitive functions that are continuous.

Then all functions definable in this language are automatically continuous.

E.g. Haskell, PCF.

#### Interpretation of recursion — introduction

A recursive definition of a function  $f: D \to E$  can always be written in the form

f(x) = F(f, x).

for a suitable continuous  $F: (D \to E) \times D \to E$ .

Equivalently,

 $f = \lambda x.F(f,x)$  or, with  $G = \bar{F}$ ,

f = G(f).

## **Interpretation of recursion** — example

fact :: Integer -> Integer
fact n = if n == 0 then 1 else n \* fact(n-1)

Take the opportunity to give the semantics of primitive functions. Now define

G :: (Integer -> Integer) -> (Integer -> Integer) G f =  $n \rightarrow if n == 0$  then 1 else n \* f(n-1)

Then the above definition is equivalent to

fact = G(fact)

#### **Interpretation of recursion — questions**

Conversely, given any  $G: (D \to E) \to (D \to E)$ , one can recursively define  $f: D \to E$  by

f = G(f).

#### Questions.

- 1. Is there any continuous function f such that f = G(f). If not, we are in trouble.
- 2. Is there more than one?
- 3. If so, which one do we choose?

#### **Interpretation of recursion** — another example

One can recursively define elements too.

```
naturals :: [Integer]
naturals = 0 : map (1+) naturals
```

Moreover, for any  $g: C \to C$  one can recursively define  $x \in C$  by

$$x = g(x).$$

# Interpretation of recursion — is it possible?

Summary:

- 1. For any continuous  $G: (D \to E) \to (D \to E)$ there must be  $f \in (D \to E)$  such that f = G(f).
- 2. For any continuous  $g \colon C \to C$

there must be  $x \in C$  with x = g(x).

But

3. With 
$$C = (D \rightarrow E)$$
 and  $g = G$  and  $x = f$ , requirement (2) is a particular case of (1).

#### Interpretation of recursion — theorem

If D is an  $\omega$ -complete poset with a least element  $\perp$ , then any continuous  $f: D \rightarrow D$  has a least fixed point.

That is:

1. There is  $x \in D$  such that x = f(x).

2. If y = f(y) then  $x \sqsubseteq y$ .

**Proof sketch**. Take  $x = \bigsqcup_n f^n(\bot)$  and show that this choice works.

## **Interpretation of recursion** — adequacy

Question. Why is it sensible to interpret recursive definitions as least fixed points?

Answer. This is justified by a theorem called *computational adequacy*, to be given later.

Roughly, this says that, with this interpretation, the denotational and the operational semantics agree at observable types.

#### **Continuity of the fixed-point operator**

Theorem. The function fix:  $(D \rightarrow D) \rightarrow D$  that sends a continuous function to its least fixed point is continuous.

Proof. Trick.

Let 
$$E = ((D \to D) \to D)$$
 and define  $\Phi \colon E \to E$  by  $\Phi(F) = \lambda f.f(Ff).$ 

Then  $\Phi$  has a least fixed point F, which is a continuous function.

But  $F = \bigsqcup_n \Phi^n(\bot) = \bigsqcup_n \lambda f. f^n(\bot) = \lambda f. \bigsqcup_n f^n(\bot).$ 

That is, F = fix, and so fix is continuous. Q.E.D.

## The functional language PCF

Scott (1969), Plotkin (1977). Streamed-down version of Haskell.

Simply typed  $\lambda$ -calculus with base types for natural numbers and booleans, and with recursion. Call-by-name evaluation.

Primitive operations: basic arithmetic and comparisons, conditional, fixed-point functionals.

It comes with a program logic, called LCF.

The domain-theoretic interpretation of PCF validates the axioms of the logic. We'll come back to this.

## **Sample application**

I'll consider a surprising program, due to Ulrich Berger (1990).

It performs a seemingly impossible task:

Given a predicate p defined on infinite sequences of bits,

it checks whether or not p holds for all infinite sequences of bits.

## **Berger's functional** — preliminaries

```
type Z = Integer
type Baire = [Z]
```

The specification of Berger's functional, to be given below, talks about infinite sequences of bits.

Let Cantor denote this subset of Baire.

We say that  $p \in (\text{Baire} \to \text{Bool})$  is defined on Cantor if  $p(\alpha) \neq \bot$  for all  $\alpha \in \text{Cantor}$ .

#### **Specification of Berger's functional**

berger :: (Baire -> Bool) -> Baire

For every  $p \in (\texttt{Baire} \rightarrow \texttt{Bool})$ , if p is defined on Cantor then

the program berger finds  $\alpha \in \text{Cantor such that } p(\alpha)$  holds, if such an  $\alpha$  exists, always returning an element of Cantor.

#### **Specification of Berger's functional** — bis

berger :: (Baire -> Bool) -> Baire

For every  $p \in (\texttt{Baire} \rightarrow \texttt{Bool})$ , if p is defined on <code>Cantor then</code>

1.  $berger(p) \in Cantor, and$ 

2.  $p(\texttt{berger}(p)) = \texttt{True} \text{ iff } p(\alpha) = \texttt{True}$ 

for some  $\alpha \in Cantor$ .

#### **Corollary:** exhaustive search over infinite sets

forsomeC, foreveryC :: (Baire -> Bool) -> Bool
forsomeC p = p(berger p)
foreveryC p = not(forsomeC(\a -> not(p a)))

equalC :: (Baire  $\rightarrow$  Z)  $\rightarrow$  (Baire  $\rightarrow$  Z)  $\rightarrow$  Bool equalC f g = foreveryC(\a  $\rightarrow$  f a == g a)

Theorem. For f and g defined on Cantor, equalC(f)(g) = True if f, g agree on Cantor, and equalC(f)(g) = False otherwise.

## **Berger's functional**

Theorem. This satisfies the above specification.

Proof. See board discussion.

## **Back to finite elements**

The proof of the above correctness result relies on finite elements.

Want notion of finite element for other domains, e.g. function spaces.

This leads to interesting and useful proof principles.

#### **Finite elements in general**

Let D be a poset with joins of ascending sequences.

**Definition**.  $b \in D$  is called finite if whenever  $b \sqsubseteq \bigsqcup_i x_i$  for some ascending sequence  $x_i$ , there there is  $x_i$  such that already  $b \sqsubseteq x_i$ .

Definition. D is called  $\omega$ -algebraic if (1) it has countably many finite elements and (2) every element of D is the join of an ascending sequence of finite elements.

## **Examples**

For  $D = \{0, 1\}^* \cup \{0, 1\}^{\omega}$  ordered by prefix, the finite elements in this abstract sense are the finite elements in the concrete sense.

Hence this domain is  $\omega$ -algebraic.

## **Examples**

Let  $\mathcal{N}$  be  $\mathbb{N} \cup \{\bot\}$  ordered by  $x \sqsubseteq y$  iff  $x = \bot$  or x = y. (Bottom is minimal, natural numbers are maximal.) This is called the flat domain of natural numbers. This is trivially algebraic: all elements are finite.

## **Examples**

Let  $D = (\mathcal{N} \to \mathcal{N}).$ 

Exercise. The elements of D are precisely the monotone functions. (Continuity trivializes.)

The following elements of D are finite:

- 1. The constant functions.
- 2. The functions  $f \in D$  such that the set  $\{n \in \mathbb{N} \mid f(n) \neq \bot\}$  has finite cardinality.

Deduce that this domain is algebraic.

#### **Functions of finite character**

Let D and E be algebraic.

Definition.  $f \in (D \to E)$  is of finite character if whenever  $c \sqsubseteq f(x)$  for  $c \in E$  finite and any  $x \in D$ , there is  $b \sqsubseteq x$  finite such that already  $c \sqsubseteq f(b)$ .

## **Characterization of continuity**

Let D and E be algebraic.

Theorem. For  $f: D \rightarrow E$  monotone, TFAE:

- 1. f is of finite character.
- 2. f is continuous.

## **Algebraic producs**

The product of two algebraic domains is algebraic.

**Exercise.** Show that  $(x, y) \in D \times E$  is finite iff x and y are finite.

## **Algebraic function spaces**

It is not the case that if D and E are algebraic then so is  $(D \rightarrow E)$ .

However, under additional assumptions on D and E, the conclusion holds.

Definition. A Scott domain is a poset that has

- 1. joins of ascending sequences,
- 2. a least element,
- 3. joins of upper bounded finite sets.

Examples. All domains we have seen so far are Scott domains.

#### Scott domains form a cartesian closed category

It is enough to show that if D and E are Scott domains then so are  $(D \times E)$  and  $(D \rightarrow E)$ .

**Exercise.** Do the  $D \times E$  case yourself.

## **Function spaces of Scott domains**

I may add a slide here. If not I'll use the board.

# The language PCF (Streicher's book version)

	$\Gamma,\!x:\sigmadash M: au$	$\Gamma \vdash M : \sigma { ightarrow}  au \ \Gamma \vdash N : \sigma$
$\overline{\Gamma,\!x:\sigma,\!\Delta\!\vdash\!x:\sigma}$	$\overline{\Gamma \vdash \lambda x.M}: \sigma { ightarrow}  au$	$\Gammadash MN: au$
	$\Gamma dash M: \texttt{nat}$	$\Gamma dash M: \texttt{nat}$
$\Gamma \vdash \texttt{zero}: \texttt{nat}$	$\overline{\Gamma \vdash \texttt{succ}M}:\texttt{nat}$	$\overline{\Gamma dash \mathtt{pred}M}:\mathtt{nat}$
$\Gamma \vdash L : \texttt{nat}  \Gamma \vdash N$	$M: \texttt{nat}  \Gamma dash N: \texttt{nat}$	$\Gamma \vdash M: \sigma { ightarrow} \sigma$
$\Gamma \vdash \texttt{if}  L  \texttt{then}  M  \texttt{else}  N : \texttt{nat}$		$\Gamma dash \mathtt{Y}M:\sigma$

#### **Big-step style operational semantics**

 $\frac{1}{x \Downarrow x} \qquad \frac{\lambda x.M \Downarrow \lambda x.M}{\lambda x.M} \qquad \frac{M \Downarrow \lambda x.L \qquad L[N/x] \Downarrow V}{MN \Downarrow V}$ 

 $\frac{M(\mathbf{Y}M)\Downarrow V}{\mathbf{Y}M\Downarrow V}$ 

#### **Big-step style operational semantics**

For  $n \in \mathbb{N}$ , write  $\underline{n} = \operatorname{succ}^{n}(\operatorname{zero})$ .

$$\frac{M \Downarrow \underline{n}}{\underline{0} \Downarrow \underline{0}} \qquad \frac{M \Downarrow \underline{n}}{\underline{\operatorname{succ}} M \Downarrow \underline{n+1}} \qquad \frac{M \Downarrow \underline{0}}{\underline{\operatorname{pred}} M \Downarrow \underline{0}} \qquad \frac{M \Downarrow \underline{n+1}}{\underline{\operatorname{pred}} M \Downarrow \underline{n}}$$

$$\frac{L \Downarrow \underline{0} \quad M \Downarrow V}{\underline{\operatorname{if}} L \operatorname{then} M \operatorname{else} N \Downarrow V} \qquad \frac{L \Downarrow \underline{n+1} \quad N \Downarrow V}{\underline{\operatorname{if}} L \operatorname{then} M \operatorname{else} N \Downarrow V}$$

#### The Scott model of PCF

This denotational semantics associates

to each type  $\sigma$ , a domain  $D_{\sigma} = \llbracket \sigma \rrbracket$ , and

to each term  $x_1 : \sigma_1, \ldots, x_n : \sigma_n \vdash M : \tau$ , a continuous function  $\llbracket M \rrbracket : \llbracket \sigma_1 \rrbracket \times \cdots \times \llbracket \sigma_n \rrbracket \to \llbracket \tau \rrbracket$ .

## **Interpretation of types**

By induction on types:

$$D_{\text{nat}} = \mathbb{N}_{\perp}$$
  $D_{\sigma \to \tau} = (D_{\sigma} \to D_{\tau})$ 

#### **Interpretation of terms**

On the above domains, define

 $\perp -1 = \perp$ , 0 - 1 = 0,  $\perp +1 = \perp$ , if  $\perp$  then x else  $y = \perp$ , if 0 then x else y = x, if n then x else y = y for  $n \neq \perp$  positive.

This gives continuous functions

$$(-+1): \mathbb{N}_{\perp} \to \mathbb{N}_{\perp} \qquad (--1): \mathbb{N}_{\perp} \to \mathbb{N}_{\perp}$$
$$(\text{if}--\text{then}--\text{else}-): \mathbb{N}_{\perp} \times \mathbb{N}_{\perp} \times \mathbb{N}_{\perp} \to \mathbb{N}_{\perp}$$

## **Interpretation of terms**

$$\begin{split} & \llbracket \Gamma \vdash \texttt{zero} \rrbracket (\vec{d}) = 0 \\ & \llbracket \Gamma \vdash \texttt{succ} \, M \rrbracket (\vec{d}) = \llbracket \Gamma \vdash M \rrbracket (\vec{d}) + 1 \\ & \llbracket \Gamma \vdash \texttt{pred} \, M \rrbracket (\vec{d}) = \llbracket \Gamma \vdash M \rrbracket (\vec{d}) - 1 \\ & \llbracket \Gamma \vdash \texttt{if} \, L \, \texttt{then} \, M \, \texttt{else} \, N \rrbracket (\vec{d}) = \\ & \quad \texttt{if} \, \llbracket \Gamma \vdash L \rrbracket (\vec{d}) \, \texttt{then} \, \llbracket \Gamma \vdash M \rrbracket (\vec{d}) \, \texttt{else} \, \llbracket \Gamma \vdash N \rrbracket (\vec{d}) \end{split}$$

# **Interpretation of terms**

$$\begin{split} \llbracket x_1 : \sigma_1, \dots, x_n : \sigma_n \vdash x_i \rrbracket (d_1, \dots, d_n) &= d_i \\ \llbracket \Gamma \vdash \lambda x.M : \sigma \to \tau \rrbracket &= \overline{\llbracket \Gamma, x : \sigma \vdash M : \tau \rrbracket} \\ \llbracket \Gamma \vdash MN \rrbracket (\vec{d}) &= \llbracket \Gamma \vdash M \rrbracket (\vec{d}) \left( \llbracket \Gamma \vdash N \rrbracket (\vec{d}) \right) \\ \llbracket \Gamma \vdash \mathbf{Y}M \rrbracket (\vec{d}) &= \operatorname{fix} \left( \llbracket \Gamma \vdash M \rrbracket (\vec{d}) \right) \end{split}$$

#### **Computational adequacy**

Theorem. For every term M of ground type with no free variables, and every  $n \in \mathbb{N}$ ,

$$\llbracket M \rrbracket = n \iff M \Downarrow \underline{n}.$$

(Hence if  $\llbracket M \rrbracket = \bot$  then there is no n such that  $M \Downarrow n$ .)

Proof. See Chapter 4 of Streicher's book.

#### The logic LCF

The following principles are validated by the Scott model: 1.  $M \sqsubseteq_{\sigma \to \tau} M' \land N \sqsubseteq_{\sigma} N' \Longrightarrow MN \sqsubseteq_{\tau} M'N'$ 1'.  $M =_{\sigma \to \tau} M' \land N =_{\sigma} N' \Longrightarrow MN =_{\tau} M'N'$ 2.  $\lambda x.M \sqsubseteq_{\sigma \to \tau} \lambda x.M' \Longrightarrow \forall x : \sigma.M \sqsubseteq M'.$ 2'.  $\lambda x.M =_{\sigma \to \tau} \lambda x.M' \Longrightarrow \forall x : \sigma.M = M'.$ 3.  $(\lambda x.M)N =_{\tau} M[N/x]$ 4.  $\lambda x : \sigma.Mx = M$  provided x is not free in M.

## The logic LCF — recursion principles

5. YM = M(YM).

6.  $\forall x : \sigma. Mx \sqsubseteq x \implies YM \sqsubseteq x.$ 

7.  $P(\perp) \land (\forall x : \sigma P(x) \implies P(Mx)) \implies P(\mathbf{Y}M).$ 

For (7) we require that

 $\boldsymbol{x}$  is not free in  $\boldsymbol{M}$  and

P(x) is a predicate built from atomic formulas using  $\forall, \land, \lor$  and  $A \implies (-)$  where A is an arbitrary formula without free occurrences of x.

## **Operational equivalence**

A.k.a. contextual equivalence, observational equivalence.

Two terms of higher type are equivalent if they produce the same answer when put in any context of ground type.

$$\begin{split} M =_{\mathrm{op}} N \text{ iff for all ground contexts } C[-], \\ C[M] \Downarrow \underline{n} \iff C[N] \Downarrow \underline{n}. \end{split}$$

Operational preorder:

$$\begin{split} M &\sqsubseteq_{\mathrm{op}} N \text{ iff for all ground contexts } C[-], \\ C[M] \Downarrow \underline{n} \implies C[N] \Downarrow \underline{n}. \end{split}$$

#### Failure of full abstraction of the Scott model

Proposition M = N implies  $M =_{op} N$ .

However, there are  $M =_{op} N$  with  $M \neq N$ .

I'll write the counter-example in Haskell.

#### **Counter-example to full abstraction (Plotkin 1977)**

```
testpor :: Int -> (Bool -> Bool -> Bool) -> Int
```

Now testpor  $0 =_{op}$  testpor 1 but testpor  $0 \neq$  testpor 1 in Scott's model.

## **Rescuing full abstraction**

Parallel-or is not definable in PCF: add it!

Then all finite elements become definable.

This implies full abstraction.

(So operational equivalence changes when you add parallel-or.)

# Universality (Plotkin 1977)

An element (or function!) is computable iff it is the join of an r.e. ascending sequence of finite elements.

There is a computable function  $\exists : (\mathbb{N}_{\perp} \to \mathbb{B}_{\perp}) \to \mathbb{B}_{\perp}$  which is not PCF definable.

$$\exists (p) = \texttt{False if } p(\bot) = \texttt{False},$$
  
 $\exists (p) = \texttt{True if } p(n) = \texttt{True for some } n \in \mathbb{B}.$ 

Theorem. PCF extended with parallel-or and exists is universal.

# Universality (Normann 1998)

Theorem. Every total computable functional is PCF definable.

## **Recursive types**

Domain equations. Language FPC. (Much closer to Haskell.) Similar programme has been developed.

## References

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